

Art Unit: 2611

—determining a posterior covariance matrix $\hat{\Sigma}_p$ of the channels using a FFT matrix W , the previous estimate of the transmitted symbol X_p , a channel convergence matrix Σ^{-1} , and a Gaussian noise variance σ^2 as $\hat{\Sigma}_p = (W^H X_p^H X_p W / \sigma^2 + \Sigma^{-1})^{-1}$;

—where determining a posterior means comprises determining a the posterior mean \hat{h}_p of a channel impulse response as $\hat{h}_p = \hat{\Sigma}_p (W^H X_p^H Y / \sigma^2 + \Sigma^{-1} E\{\underline{h}\})$, where the received symbol is Y , and $E\{\underline{h}\}$ is a the channel impulse response;

—determining a channel update coefficients matrix C for recovering the next estimate of the transmitted symbol; and

applying the coefficient matrix C to the posterior mean \hat{h}_p , the FFT matrix W , and the received symbol Y according to $\tilde{X}_{p+1} = C^{-1} (\hat{h}_p^H W^H Y)^T$ to optimize the next estimate of the transmitted symbol \tilde{X}_{p+1} .

Regarding claim 11, in line 4, "symbol transmitted" is replaced by -transmitted **NB 5/11/06** symbol--.

Regarding claim 18, the following version replaces all prior versions in their entirety:

18. The system of claim 12 further comprising:

—means for determining a posterior covariance matrix $\hat{\Sigma}_p$ of the channels using the FFT matrix W , the initial estimate of the transmitted symbol X_p , a channel convergence matrix Σ^{-1} , and a Gaussian noise variance σ^2 as $\hat{\Sigma}_p = (W^H X_p^H X_p W / \sigma^2 + \Sigma^{-1})^{-1}$;

—where the means for determining a posterior mean comprises means for determining a the posterior mean \hat{h}_p of a channel impulse response as $\hat{h}_p = \hat{\Sigma}_p (W^H X_p^H Y / \sigma^2 + \Sigma^{-1} E\{\underline{h}\})$, where the received symbol is Y and $E\{\underline{h}\}$ is a the channel impulse response;